



Why discrete-time Petri Nets with stopwatches?

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Introduction

Before selling a new model to its clients, a car manufacturer must be **sure of the quality** of its vehicle. Among all, the **correctness** of the whole computational architecture constitutes a critical factor (a car can now contain more than thirty processors). If some bugs remain, the fall-outs may be disastrous not only for the image of the company, but also for the safety of the driver.

As systems demanding correctness proofs increase in complexity, their validation cannot be achieved by an exhaustive simulation of all their potential behaviors. Thus efficient formalisms, like Time Petri Nets (TPNs), and model-checking techniques are needed.

TPNs are however not expressive enough to **model the preemptive scheduling of tasks**, *i.e.* actions that can be suspended and resumed. That is why an extension of TPNs that addresses the modeling of stopwatches (instead of simple clocks) have been introduced: **Stopwatches Petri Nets (SwPNs)**. The complexity of the SwPN model is such that many problems have been proven **undecidable** as long as a dense-time analysis is considered. That means there will never be any automatic procedure that computes the state space of the net. In order to obtain a finite abstraction of the state space, we apply a **discrete-time approach** instead of a dense-time one.

Petri Nets with Stopwatches

Petri Nets with stopwatches [1] (SwPNs for short) are a time extension of classical Petri Nets. They allow to represent easily common structures in timed systems: synchronisation, parallelism, mutual exclusion, preemption ... Informally, to each transitions of the net is associated a **stopwatch** and a **time interval**. The clock measures the time since the transition was enabled and the time interval is interpreted as a firing condition: the transition may fire if its clock value belongs to the time interval.

In the **dense-time approach**, time is considered as a *continuous* variable whose evolution goes at rate 1. By contrast, in the **discrete time approach**, time is seen as "jumping" from one integer to the other, with no care of what may happen in between. The latter is an under-approximation of the former.

The semantics of a discrete-time SwPN consists in two different actions:

- a **discrete** transition: the firing of an enabled transition,
- a **discrete-time** transition: the net stays in its current marking while time is increasing of one time unit.

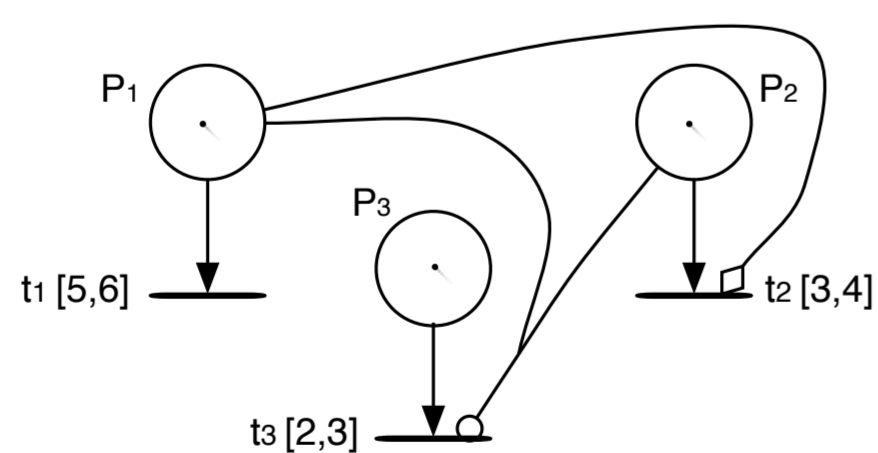


Figure 1: A Stopwatch Petri net

In figure 1, the inhibitor hyperarc prohibits the firing of t_3 as long as there is a token in P_1 and P_2 . The stopwatch associated to transition t_3 is then **stopped**; it is **resumed** once one of these two places does not contain any token anymore. Whatever the marking of P_1 is, it is set to 0 when t_2 is fired. There is indeed a flush arc between P_1 and t_2 .

SwPNs enable us to design real-time systems. It is then possible to verify on the resulting model whether the behavior of the system verifies its **specifications** *i.e.* a set of given properties. We are especially interested in *safety properties*, that are properties claiming that *nothing wrong will happen*. Such properties can be interpreted as a **marking reachability problem**. Thus the computation of the Petri net state space is needed.

Analyzing a discrete-time bounded SwPN

Why working with discrete-time instead of dense-time?

The marking reachability problem has been proven undecidable for dense-time SwPNs. On the contrary, we have proven the following theorem:

Theorem 1 *The marking reachability problem is decidable for discrete-time bounded SwPNs.*

This implies the discrete-time approach leads to a **finite state space abstraction** even for nets whose dense-time state space computation does not terminate.

An efficient method for computing the state space of SwPNs

In the time extensions of Petri nets, temporal information is modelled **implicitly**. In [2], we have proven the following result: as far as discrete-time is considered, it is possible to **simulate the elapsing of time** with a special *tick* transition added to the classical Petri net formalism. The clock associated to each transition is then viewed as a place whose marking ranges over the domain of natural numbers and is incremented by one with every tick transition. Thus the state space of discrete-time bounded SwPNs can be computed directly by *using existing tools for classical (untimed) Petri nets* like Markg [3].

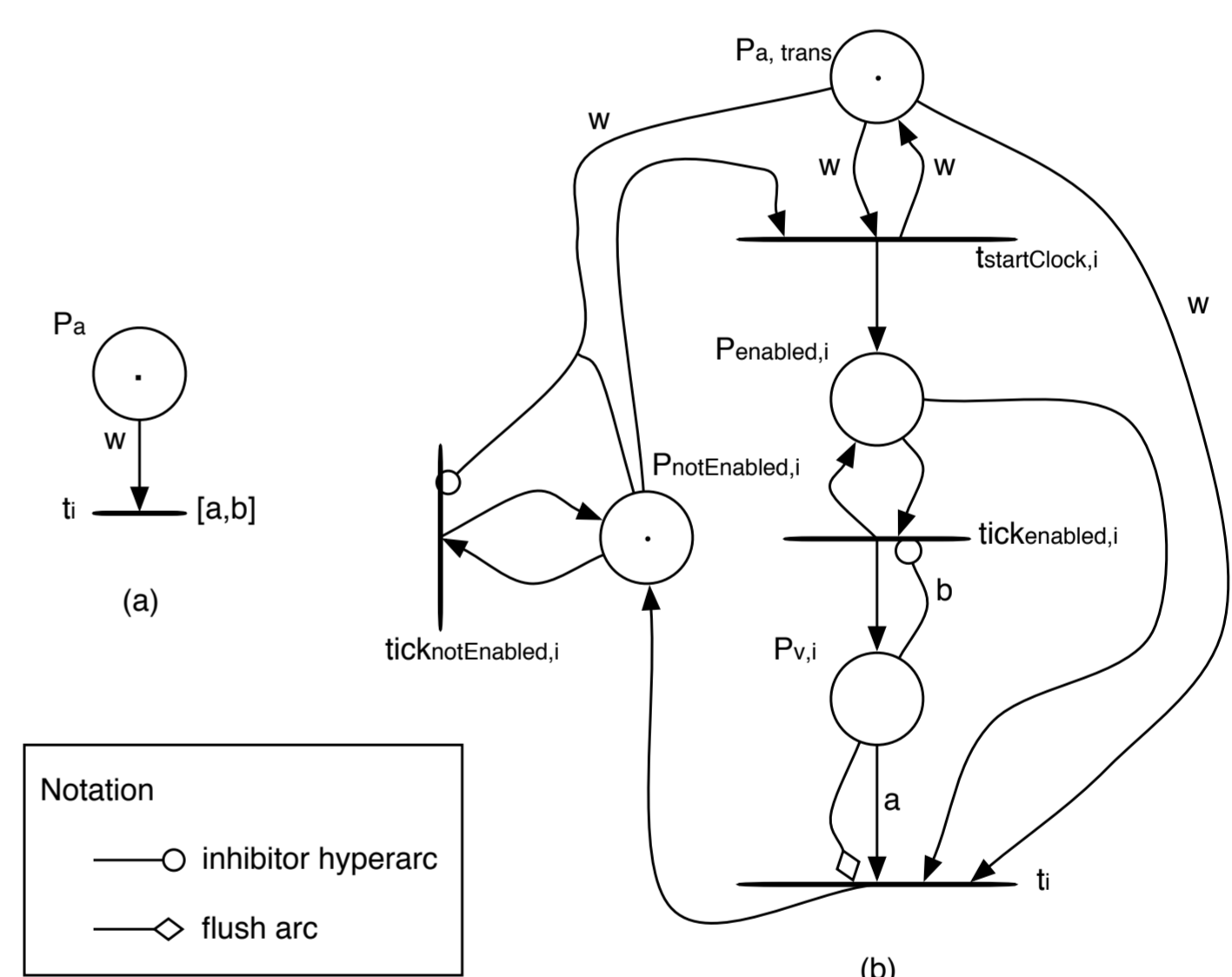


Figure 2: A simple example: translating a TPN into an untimed Petri net

Experimental results comparing the discrete-time state space computation and the dense-time one show that the discrete-time approach is **interesting for many systems of practical interest**.

References

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- [3] P. Molinaro and M. Magnin. Markg. Available at <http://markg.rts-software.org>, 2006.